



Calculator-assumed

ATAR course examination 2019

Marking key

Marking keys are an explicit statement about what the examining panel expect of candidates when they respond to particular examination items. They help ensure a consistent interpretation of the criteria that guide the awarding of marks.

Section Two: Calculator-assumed

Question 10

65% (85 Marks)

(5 marks)

The sketch of the locus of a complex number z = x + iy is shown below.



(a) Given that the equation for the above locus is written as $Arg(z-z_0) = k\pi$, determine the value of the constants z_0 and k. (2 marks)

Solution
The equation can be read as the argument of z from z_0 is equal to $k\pi$.
i.e. $Arg(z-(-2i)) = \frac{\pi}{4}$ i.e. $z_0 = -2i$, $k = \frac{1}{4}$
Specific behaviours
\checkmark states the correct value for z_0
\checkmark states the correct value for k

(b) Determine the minimum value for |z-i| as an exact value. (3 marks)

Solution
We require the minimum distance of a point in the locus from $z = i$ (point A).
This will be the perpendicular distance AB to the locus.
Point <i>B</i> will be the point $(1.5, -0.5i)$. Hence $AB = \sqrt{\left(\frac{3}{2}\right)^2 + \left(\frac{3}{2}\right)^2} = \sqrt{\frac{18}{4}} = \frac{3\sqrt{2}}{2}$
Hence the minimum value for $ z-i = \frac{3\sqrt{2}}{2}$.
Specific behaviours
\checkmark indicates how the minimum value $ z-i $ is found
\checkmark determines coordinates for point <i>B</i> correctly
\checkmark determines the minimum value $\left z-i\right $ correctly

(6 marks)

The slope field given by
$$\frac{dy}{dx} = \frac{x}{2y+2}$$
 is shown in the diagram below.



(a) Calculate the value of the slope field at the point (2,0). (1 mark)

Solution
Evaluating $\frac{dy}{dx}$ when $x = 2$, $y = 0$: $\frac{dy}{dx} = \frac{2}{2(0)+2} = 1$
i.e. the slope field at $(2,0)$ has a value of 1.
Specific behaviours
\checkmark evaluates $\frac{dy}{dx}$ correctly

(b) On the diagram above, draw the solution curve that contains the point (2,0). (2 marks)

Solution
Shown above on the diagram.
Specific behaviours
✓ draws a curve that follows the slope field
\checkmark draws a curve that is vertical at $y = -1$ or symmetric about $y = -1$

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Question 11 (continued)

(c) Determine the equation for the solution curve that contains the point (2,0). (3 marks)

Solution
Separating variables obtains $\int (2y+2) dy = \int x dx$
$\therefore y^2 + 2y = \frac{x^2}{2} + c$
Using $(2,0): 0^2 + 2(0) = \frac{2^2}{2} + c$ $\therefore c = -2$
Equation of the solution through (2,0) is $y^2 + 2y = \frac{x^2}{2} - 2$
Alternatively: $(y+1)^2 = \frac{x^2}{2} - 1$ OR $y = \pm \sqrt{\frac{x^2}{2} - 1} - 1$
Specific behaviours
\checkmark separates the variables correctly
✓ anti-differentiates correctly using a constant
✓ determines the anti-derivative constant correctly

Let $w = \frac{1-i}{2\sqrt{2}}$.

(a) Express w in the form
$$w = r \operatorname{cis} \theta$$
, where $-\pi < \theta \le \pi$. (2 marks)

Solution
$w = \frac{1-i}{2\sqrt{2}} = \frac{\sqrt{2}cis\left(-\frac{\pi}{4}\right)}{2\sqrt{2}} = \frac{1}{2}cis\left(-\frac{\pi}{4}\right)$
Specific behaviours
\checkmark determines the correct modulus <i>r</i>
\checkmark determines the correct argument θ

The complex number z is represented in the Argand diagram below.



(b) Express z exactly in the form z = a + bi.

(2 marks)

SolutionFrom the Argand diagram
$$z = 4cis\left(\frac{2\pi}{3}\right)$$
Hence $z = 4\left(\cos\frac{2\pi}{3} + i\sin\frac{2\pi}{3}\right) = 4\left(-\frac{1}{2} + i\frac{\sqrt{3}}{2}\right) = -2 + 2\sqrt{3}i$ Specific behaviours \checkmark determines the polar form for z correctly (interprets the Argand diagram) \checkmark determines the correct exact values for a, b

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(10 marks)

(2 marks)

Question 12 (continued)

(c) Determine the exact polar form for wz and w^2z .

Solution
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Given $w = \frac{1}{2} cis\left(-\frac{\pi}{4}\right)$ and $z = 4 cis\left(\frac{2\pi}{3}\right)$
Then $wz = \frac{1}{2} \times 4 \operatorname{cis}\left(-\frac{\pi}{4} + \frac{2\pi}{3}\right) = 2\operatorname{cis}\left(\frac{5\pi}{12}\right)$
Also $w^2 z = \left(\frac{1}{2}\right)^2 \times 4 \times cis\left(-\frac{\pi}{2} + \frac{2\pi}{3}\right) = 1cis\left(\frac{\pi}{6}\right)$
Specific behaviours
\checkmark determines the correct modulus for both wz and w^2z
\checkmark determines the correct argument for both wz and w^2z

(d) On the Argand diagram on page 6, plot the position for wz and w^2z . Ensure that each position is labelled clearly. (2 marks)

Solution
Indicated on the Argand diagram.
Specific behaviours
\checkmark indicates the correct modulus for both wz and w^2z (distance from origin)
\checkmark indicates the correct argument for both wz and w^2z (angle to real axis)

Consider the geometric transformation(s) applied to transform $z \rightarrow wz \rightarrow w^2 z \rightarrow w^3 z$ etc.

(e) Describe the geometric transformation(s) performed by the successive multiplication by *w*. (2 marks)

Solution
Successive multilplication by <i>w</i> results in the modulus changing by a factor of $\frac{1}{2}$
(successive points becoming twice as close to the origin) and the argument
decreasing by 45° or $\frac{\pi}{4}$.
Geometric description: Each vector is REDUCED by a factor of 0.5 .
Each vector is ROTATED clockwise (about origin) by 45°
Specific behaviours
\checkmark describes the change in the modulus a dilation by factor 0.5
\checkmark describes the change in the argument as a clockwise rotation by 45° or $rac{\pi}{4}$

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MATHEMATICS SPECIALIST

Question 13

(10 marks)

The path of a particle is shown below. This particle moves so that its position vector r(t) is

given by
$$r(t) = \begin{pmatrix} -2\cos(\frac{t}{2}) \\ 1-\sin(t) \end{pmatrix}$$
 metres, where *t* is the number of seconds the particle has

been in motion.



(a) Determine the starting position of the particle and mark this as point *A* on the diagram above. (1 mark)

Solution

 Substituting
$$t = 0$$
 $r(0) = \begin{pmatrix} -2\cos(0) \\ 1-\sin(0) \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$

 Specific behaviours

 \checkmark indicates the point (-2,1) on the diagram correctly

(b) Determine the initial velocity of the particle and illustrate this on the diagram above. (3 marks)

Solution
$ \underbrace{\psi(t) = \frac{d\underline{r}}{dt} = \begin{pmatrix} \sin\left(\frac{t}{2}\right) \\ -\cos(t) \end{pmatrix} \text{ Substituting } t = 0 \underbrace{\psi(0) = \begin{pmatrix} \sin\left(\frac{0}{2}\right) \\ -\cos(0) \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}} $
Specific behaviours
\checkmark determines $y(t)$ by differentiating BOTH components correctly
\checkmark evaluates $v(0)$ correctly
\checkmark indicates a vector representing $v(0)$ on the diagram correctly

Question 13 (continued)

(c) Write the expression, in terms of trigonometric functions, for the distance the particle would travel in completing one circuit of the given path. Do **not** evaluate this expression. (3 marks)

Solution
One circuit is completed when
$$-2\cos\frac{t}{2} = -2$$
 i.e. $t = 0, 4\pi, ...$
Distance travelled for one circuit $= \int_{0}^{4\pi} Speed(t) dt = \int_{0}^{4\pi} |y(t)| dt$
 $= \int_{0}^{4\pi} \sqrt{\sin^2(\frac{t}{2}) + \cos^2(t)} dt$
Specific behaviours
 \checkmark forms a definite integral using the correct limits $t = 0, 4\pi$
 \checkmark writes the correct expression for the speed function in terms of t using trigonometric functions

- ✓ uses correct mathematics notation for vectors and the definite integral
- (d) Determine the Cartesian equation for the path of the particle.

(3 marks)

Solution
We have
$$x = -2\cos\left(\frac{t}{2}\right)$$
 i.e. $\cos\left(\frac{t}{2}\right) = -\frac{x}{2}$
and $y = 1 - \sin(t)$ i.e. $\sin(t) = 1 - y$
 $\cos\left(2\left(\frac{t}{2}\right)\right) = 2\cos^2\left(\frac{t}{2}\right) - 1$ \therefore $\cos(t) = 2\left(-\frac{x}{2}\right)^2 - 1 = \frac{x^2}{2} - 1$
Since $\sin^2\theta + \cos^2\theta = 1$ then the Cartesian equation becomes
 $(1 - y)^2 + \left(\frac{x^2}{2} - 1\right)^2 = 1$ Alternative forms: $1 - 2y + y^2 + \frac{x^4}{4} - x^2 = 0$
 $(y - 1)^2 = 1 - \left(\frac{x^2}{2} - 1\right)^2$ or $y = 1 \pm \sqrt{1 - \left(\frac{x^2}{2} - 1\right)^2}$
Specific behaviours
 \checkmark forms correct expressions for $\cos\left(\frac{t}{2}\right)$ and $\sin(t)$ correctly in terms of x, y
 \checkmark uses the double angle identity to obtain trigonometric equations with the same
variable (either both in terms of $\frac{t}{2}$ or t)
 \checkmark uses the identity $\sin^2\theta + \cos^2\theta = 1$ correctly to eliminate t to obtain the Cartesian
equation

(10 marks)

(2 marks)

Trucks carrying iron ore for the Croc Rock mining company arrive at a weighing station. The service time T per truck is defined to be the time elapsed from the moment a truck enters the station zone, including the time to be positioned and then weighed, up to the time it leaves the zone.

It is known that the population mean $\mu(T) = 80$ seconds and the population standard deviation $\sigma(T) = 20$ seconds.

At the Croc Rock weighing station, 100 trucks are weighed.

(a) State the (approximate) distribution of the sample mean service time per truck for the 100 trucks. (3 marks)

Solution

$$\overline{T}$$
 is approximately normally distributed as the sample size $n = 100 > 30$
 $\overline{T} \sim N\left(80, \frac{20^2}{100}\right) = N(80, 4)$
i.e. $\sigma(\overline{T}) = \sqrt{4} = 2$

 Specific behaviours

 \checkmark states the sample mean is normally distributed (or refers to the Central Limit Theorem)

 \checkmark states the correct mean

 \checkmark states the correct standard deviation (or variance)

(b) What is the probability that the sample mean service time will be more than 83 seconds?

Solution

$$P(\overline{T} > 83) = P\left(z > \frac{83 - 80}{2}\right) = P(z > 1.5)$$
 $= 0.067$

 Specific behaviours

 \checkmark calculates/uses the correct z scores

 \checkmark determines the correct probability

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Question 14 (continued)

Suppose that more than 100 trucks were weighed at the Croc Rock weighing station.

(c) How would this affect your answer to part (b)? Explain without recalculation. (2 marks)

Solution
Since for $n > 100$ would result in $\sigma(\overline{T}) < 2$, then the mean time of 83 minutes would
be a more of an extreme sample mean in the normal distribution.
Hence there would be a lower probability that $P(\overline{T} > 83)$.
i.e. the answer to part (b) would be LOWER.
Specific behaviours
✓ States that the answer would decrease
\checkmark Justifies by reference to the lower standard deviation of the sample mean OR that
83 minutes becomes a relatively more extreme score

It is desired that the probability that the sample mean service time will be between 80 seconds and 82 seconds is greater than 40%.

(d) Determine the minimum number of trucks that will need to be weighed. (3 marks)

SolutionRequire $P(80 < \overline{T} < 82) > 0.4$ i.e. P(0 < z < k) > 0.4 $\therefore k > 1.282$ Hence $\frac{82-80}{\frac{20}{\sqrt{n}}} > 1.282$ Solving gives n > 164.35 \therefore At least 165 trucks are required to be weighed.Specific behaviours \checkmark calculates the critical z score for 82 minutes \checkmark forms the inequality or equation to solve for the number of trucks \checkmark states the minimum number of trucks to be weighed as an integer

(9 marks)

A random sample of *n* commuters in Melbourne in August 2018 found that the average time to commute to work was 40 minutes. Repeated sampling of the mean indicated that the standard deviation of the sample mean was 3 minutes.

(a) Determine a 90% confidence interval for the population mean commuting time μ to work, correct to 0.01 minutes. (3 marks)

Solution
90% confidence interval for μ : $P(-k < z < k) = 0.9$ yields $k = 1.645$
$40 - 1.645(3) < \mu < 40 + 1.645(3)$
i.e. $35.06 < \mu < 44.94$ minutes
Specific behaviours
\checkmark uses the critical z score for 90% confidence
\checkmark forms the correct expression for the confidence interval limits (using $\sigmaig(\overline{X}ig)\!=\!3$)
\checkmark determines the upper and lower limit correctly (no penalty for incorrect rounding)

Another random sample of 2n commuters in November 2018 found that the average time to commute to work was 45 minutes. Assume that both the August and November samples were drawn from the same population.

(b) What is the standard deviation of the sample mean for the November sample, correct to 0.01 minutes? (2 marks)

Colution	
Solution	
Let σ = the population standard deviation for the commuting time (minutes)	
From August sample we have $\frac{\sigma}{\sqrt{n}} = 3$ i.e. $\sigma = 3\sqrt{n}$	
For November sample we require : $\sigma(\overline{X}) = \frac{\sigma}{\sqrt{2n}} = \frac{1}{\sqrt{2}} \left(\frac{\sigma}{\sqrt{n}}\right)$	
$= \frac{1}{\sqrt{2}}(3) = 2.12 \text{ min} (2 \text{ d.p.})$	
Specific behaviours	
\checkmark forms the correct relationship between the standard deviations OR states that	
$\sigma = 3\sqrt{n}$ (or its equivalent)	
\checkmark determines the standard deviation of sample mean correct to 0.01 minutes	

✓ determines the standard deviation of sample mean correct to 0.01 minutes

Question 15 (continued)

Suppose that the August and November samples are combined to form a sample with 3n commuters. Consider 90% confidence intervals for the following samples for the purpose of determining the population mean commuting time μ .

90% confidence interval	Sample Size	
A	August	п
N	November	2 <i>n</i>
С	Combined	3 <i>n</i>

(c) Which of the three confidence intervals, A, N or C, will provide the greatest precision in determining the population mean μ ? Justify your answer. (2 marks)

Solution		
C is the most precise, as it is based on the smallest standard error (standard deviation		
of the sample mean)		
Specific behaviours		
✓ states that C will provide the greatest precision		
\checkmark provides a valid reason (smallest standard deviation in the sample mean or largest		
sample size)		

(d) Which of the three confidence intervals, A, N or C, contains the true value of the population mean μ ? Justify your answer. (2 marks)

Solution		
We do not know which interval contains the population mean μ . This is because we		
do not know the true value of μ OR that by random sampling we cannot be certain		
which interval contains μ .		
Specific behaviours		
\checkmark states that we do not know which interval contains the population mean		
\checkmark provides a valid reason (either μ is not known OR that by random sampling we		
cannot be certain which interval contains μ)		

CALCULATOR-ASSUMED

Question 16

Plane \prod_1 has Cartesian equation z = 2x + y + 4.

(a) Determine a vector that is normal to plane \prod_{1} .

Solution Cartesian equation can be written as 2x + y - z = -4. $\therefore \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -4$ is the vector normal form for plane Π_1 . Hence the vector $2\underline{i} + \underline{j} - \underline{k}$ is perpendicular (the normal) to plane Π_1 . Specific behaviours

Specific behaviours \checkmark re-writes the Cartesian form into vector form OR into standard Cartesian form. \checkmark states the vector perpendicular to plane Π_1

Line *L* has equation
$$r = \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$
.

(b) Determine the point of intersection between line L and plane Π_1 . (3 marks)

Solution		
Line <i>L</i> has equation $r = \begin{pmatrix} 2+\lambda \\ 2\lambda \\ 3-\lambda \end{pmatrix}$		
Solving simultaneously: $\therefore \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \begin{pmatrix} 2+\lambda \\ 2\lambda \\ 3-\lambda \end{pmatrix} = -4$		
i.e. $2(2+\lambda)+1(2\lambda)-1(3-\lambda) = -4$		
i.e. $5\lambda + 1 = -4$		
i.e. $\lambda = -1$ Hence intersection point is $(1, -2, 4)$.		
Specific behaviours		
\checkmark substitutes the expression for line vector correctly into equation for plane		
\checkmark solves correctly for the value of parameter λ		
\checkmark states the point of intersection (can be either in vector or Cartesian form)		

(12 marks)

(2 marks)

14

Question 16 (continued)

Plane Π_2 contains line L and is perpendicular to plane Π_1 .

(c) Determine the vector equation for plane Π_2 .

(4 marks)

Solution	
Let n_2 be the normal vector for plane \prod_2 .	
Hence n_2 is perpendicular to d direction vector of the line <i>L</i> AND to the normal n_1	
of plane Π_1 . Hence $\underline{n}_2 = \underline{n}_1 \times \underline{d} = \begin{pmatrix} 2\\1\\-1 \end{pmatrix} \times \begin{pmatrix} 1\\2\\-1 \end{pmatrix} = \begin{pmatrix} 1\\1\\3 \end{pmatrix}$	
A point in plane \prod_2 can be any point on Line <i>L</i> i.e. $(2,0,3)$	
Vector equation for Π_2 : $\underline{r} \cdot \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = 11$	
Note: Cartesian equation for $\prod_2 : x + y + 3z = 11$	
Specific behaviours	
\checkmark states that the normal n_2 is perpendicular to both d and n_1	
\checkmark determines the vector \underline{n}_2 (by cross product or otherwise)	
\checkmark uses correctly a point of L as a point for plane \prod_2	
\checkmark forms the vector equation for plane \prod_2 correctly	

or

Alternative Solution		
The vector equation for plane \prod_2 is given by :		
$r = \begin{pmatrix} 2\\0\\3 \end{pmatrix} + \lambda \begin{pmatrix} 1\\2\\-1 \end{pmatrix} + \mu \begin{pmatrix} 2\\1\\-1 \end{pmatrix} \text{i.e.} r = \begin{pmatrix} 2+\lambda+2\mu\\2\lambda+\mu\\3-\lambda-\mu \end{pmatrix}$		
This is because \prod_2 contains line L so it contains the point $ig(2,0,3ig)$ and contains		
the direction vector $(1, 2, -1)$ of line <i>L</i> . Also plane \prod_2 has to be in a direction that is		
normal to \prod_{1} hence we can move in the direction $(2,1,-1)$.		
Specific behaviours		
\checkmark uses the known point (2,0,3) in writing the vector equation using two directions		
\checkmark uses two different parameters with the two directions		
✓ uses the direction vector $(1,2,-1)$ for line <i>L</i> correctly		
✓ uses the normal vector $(2,1,-1)$ for plane \prod_1 correctly		

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Sphere *S* has vector equation $\left| \dot{r} - \left(3\dot{i} + \dot{j} + 4\dot{k} \right) \right| = \sqrt{35}$.

(d) Determine whether line *L* is a tangent to sphere *S*. Justify your answer. (3 marks)

SolutionExamine how many points of intersection there are between the line and the sphere.To find the intersection solve simultaneously : $\begin{pmatrix} 2+\lambda \\ 2\lambda \\ 3-\lambda \end{pmatrix} - \begin{pmatrix} 3 \\ 1 \\ 4 \end{pmatrix} \end{vmatrix} = \sqrt{35}$ i.e. $(\lambda - 1)^2 + (2\lambda - 1)^2 + (-1-\lambda)^2 = 35$ $\therefore 6\lambda^2 - 4\lambda - 32 = 0$ $\therefore 6\lambda^2 - 4\lambda - 32 = 0$ $\therefore \lambda = -2$ or $\lambda = \frac{8}{3}$ \therefore There are 2 points of intersection. \therefore The line is NOT a tangent.Specific behaviours \checkmark obtains the equation that determines the intersection \checkmark solves correctly to determine the parameter λ \checkmark justifies that the 2 points of intersection means the line is not a tangent

or

Alternative Solution	
Determine the shortest distance from the centre of the sphere to the line.	
Using point $A(2,0,3)$ on line L and centre of sphere $C(3,1,4)$.	
Hence $\overrightarrow{AC} = (1,1,1)$.	
Shortest distance from point <i>C</i> to line <i>L</i> = $\frac{\left \vec{AC} \times \vec{d}\right }{\left \vec{d}\right } = \frac{\left (1,1,1) \times (1,2,-1)\right }{\left (1,-2,1)\right } = \frac{\left (-3,2,1)\right }{\sqrt{6}} = \frac{\sqrt{14}}{\sqrt{6}} = \sqrt{\frac{7}{3}} = 1.527$	
Since the radius of sphere $\sqrt{35} > \sqrt{\frac{7}{3}}$ then there will be two points of intersection.	
Specific behaviours	
\checkmark forms the correct expression for the shortest distance	
✓ calculates the shortest distance correctly	

✓ justifies that the radius > shortest distance means the line is not a tangent

16

Question 17

(8 marks)

In Australia, the killing of humpback whales was banned in 1963.

At the end of 2018, 45 years later, the population P of migrating humpback whales off the coast of Western Australia was estimated at 30 000, i.e. $P(45) = 30\ 000$.

(a) Assuming that the population of humpback whales had been increasing at an instantaneous rate equal to 10% of the population, estimate the number of humpback whales at the end of 1963.
 (3 marks)

Solution using $P(45) = 30\ 000$		
Rate of change is given by $\frac{dP}{dt} = 0.1P$. This has solution $P(t) = P_0 e^{0.1t}$		
Using $P(45) = 30\ 000\ 30\ 000\ =\ P_0 e^{0.1(45)}$		
Solving gives $P_0 = 333.26$		
i.e. there were 333 humpback whales at the end of 1963.		
(answers 300 or 330 are acceptable given the initial information)		
Specific behaviours		
\checkmark forms the differential equation correctly to represent the rate of change		
\checkmark writes the specific exponential solution for this differential equation		
\checkmark uses $P(45) = 30\ 000$ to correctly deduce $P(0)$ as an integer value		

or

Solution using $P(55) = 30\ 000$	
Rate of change is given by $\frac{dP}{dt} = 0.1P$. This has solution $P(t) = P_0 e^{0.1t}$	
Using $P(55) = 30\ 000$ 30 000 = $P_0 e^{0.1(55)}$	
Solving gives $P_0 = 122.60$	
i.e. there were 123 humpback whales at the end of 1963.	
(answers 100 or 120 are acceptable given the initial information)	
Specific behaviours	
\checkmark forms the differential equation correctly to represent the rate of change	
\checkmark writes the specific exponential solution for this differential equation	
✓ uses $P(55) = 30\ 000$ to correctly deduce $P(0)$ as an integer value	

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(2 marks)

To model the growth in the population from the end of 2018, a marine biologist suggests that the rate of growth be modelled by the equation below.

$$\frac{dP}{dt} = 0.1P - \frac{P^2}{700\ 000}$$

The biologist re-defines $P(0) = 30\ 000$, i.e. t = number of years from the end of 2018.

(b) If P(t) is written in the form $P(t) = \frac{a}{1 + be^{-ct}}$, determine the values of the constants

a, b and c.

Solution $\frac{dP}{dt} = 0.1P - \frac{P^2}{700\,000} = \frac{P}{10} - \frac{P^2}{700\,000} = \frac{1}{700\,000}P(70\,000 - P)$ From formula sheet $\frac{dP}{dt} = rP(k - P)$ gives $P = \frac{kP_0}{P_0 + (k - P_0)e^{-rkt}}$ As $P(0) = 30\,000$, then $P(t) = \frac{(70\,000)(30\,000)}{30\,000 + (70000 - 30\,000)e^{-0.1t}}$ $\therefore P(t) = \frac{70\,000}{1 + \frac{4}{3}e^{-0.1t}}$ i.e. $a = 70\,000$, $b = \frac{4}{3}$, c = 0.1Specific behaviours \checkmark determines the correct value of constant a \checkmark determines the correct value of the constants b, c

(c) Hence determine the year during which the population of humpback whales off the coast of Western Australia will reach double that estimated at the end of 2018. (2 marks)

SolutionRequire when $P(t) = 60\,000$.i.e. Solve $\therefore 60\,000 = \frac{70\,000}{1 + \frac{4}{3}e^{-0.1t}}$ $\therefore e^{-0.1t} = \frac{1}{8}$ i.e. $t = 10(\ln 8)$ Using CAS t = 20.794... yearsHence the population is estimated to double during year 2039.Specific behaviours \checkmark forms the correct equation to solve for t \checkmark solves and concludes the calendar year for the population to double

Question 17 (continued)

(d) State the major difference in the variation in the population P(t) using the model in part (b) compared with that in part (a). (1 mark)

Solution
The rate of growth in part (b) will increase from $P = 30\ 000$ to $P = 35\ 000$ and then
the rate of growth decreases from $P = 35\ 000$ to approach an equilibrium or steady
state population of $P = 70\ 000$ i.e. part (b) model represents limited growth.

In part (a), the model will predict that growth will continue without any limit. Specific behaviours

 \checkmark states a valid property that distinguishes the growth in part (b) from part (a)

(11 marks)

A ferris wheel has a radius of 80 metres and rotates in an anticlockwise direction at a rate of one revolution every 72 seconds. The ferris wheel has 16 cars that are equally spaced around the wheel as shown in the diagram.

A coordinate system is set up so that the centre of the ferris wheel is at the origin and the ground level has equation y = -80. Passengers begin their ride when a car is at position A (0, -80).

Consider a passenger in a car at position P.

- Let t = the number of seconds the ride has been in progress from position A.
 - θ = the angle in radians that the car has rotated from position A.
 - y = the height of a car above the centre of the ferris wheel (metres).



(a) Show that $\frac{d\theta}{dt} = \frac{\pi}{36}$ radians per second.

(1 mark)

Solution		
One revolution $(2\pi \text{ radians})$ every 72 seconds means	$\frac{d\theta}{dt} = \frac{2\pi}{72} = \frac{\pi}{36}$	
Specific behaviours		
\checkmark states that the angle changes 2π radians every 72 seconds		

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Question 18 (continued)

(b) Given that
$$y(\theta) = 80\sin(\theta + \alpha)$$
, explain why $\alpha = -\frac{\pi}{2}$. (1 mark)

Solution Using y(0) = -80 then $-80 = 80\sin(\alpha)$ i.e. $\sin(\alpha) = -1$ $\therefore \alpha = -\frac{\pi}{2}$ OR at position *P* the angle above the *x* axis is equal to $\theta - \frac{\pi}{2}$ $\therefore \alpha = -\frac{\pi}{2}$ Specific behaviours \checkmark justifies correctly the value for α

(c) Determine how quickly a passenger is moving upward when they are 100 metres above the ground, correct to the nearest 0.01 metres per second. (4 marks)

SolutionWhen 100 metres above ground,
$$y = 100 - 80 = 20$$
 $\therefore 20 = 80 \sin\left(\theta - \frac{\pi}{2}\right)$ i.e. $\sin\left(\theta - \frac{\pi}{2}\right) = \frac{1}{4}$ i.e. $\theta = 1.823...$ Hence $\cos\left(\theta - \frac{\pi}{2}\right) = \sqrt{1 - 0.25^2} = \frac{\sqrt{15}}{4} = 0.9682...$ OR $\therefore 20 = 80 \sin\left(\frac{\pi t}{36} - \frac{\pi}{2}\right)$ i.e. $t = 20.8955...$ secAs $y = 80 \sin\left(\theta - \frac{\pi}{2}\right)$ then differentiating both sides with respect to t $\frac{dy}{dt} = \frac{dy}{d\theta} \times \frac{d\theta}{dt} = 80 \cos\left(\theta - \frac{\pi}{2}\right) \times \frac{\pi}{36}$ $= 80 \left(\frac{\sqrt{15}}{4}\right) \left(\frac{\pi}{36}\right) = 6.7596...$ m/secHence the passenger is moving up at a rate of 6.76 m/sec (nearest 0.01)Specific behaviours \checkmark deduces $y = 20$ \checkmark differentiates correctly using the the chain rule to obtain an expression for $\frac{dy}{dt}$ \checkmark substitutes either $\cos\left(\theta - \frac{\pi}{2}\right) = \frac{\sqrt{15}}{4}$ or $t = 20.8955$ or $\theta = 1.823...$

(d) Show that function y(t) satisfies the condition for simple harmonic motion. (2 marks)

Solution
Need to show that $y''(t) = -n^2 y(t)$
$y(t) = 80\sin\left(\frac{\pi t}{36} - \frac{\pi}{2}\right)$ Hence $y'(t) = 80\cos\left(\frac{\pi t}{36} - \frac{\pi}{2}\right) \times \frac{\pi}{36}$
$\therefore y''(t) = 80 \times \frac{\pi}{36} \times \left(-\sin\left(\frac{\pi t}{36} - \frac{\pi}{2}\right)\right) \times \frac{\pi}{36}$
$= -\left(\frac{\pi}{36}\right)^2 \times 80\sin\left(\frac{\pi t}{36} - \frac{\pi}{2}\right) = -\left(\frac{\pi}{36}\right)^2 y(t)$
Hence function $y(t)$ satisfies the definition for simple harmonic motion.
Specific behaviours
\checkmark differentiates twice correctly to find $y''(t)$ correctly
\checkmark shows that $y''(t) = -n^2 y(t)$ where it is evident that $n = \frac{\pi}{36}$

A different passenger happens to be in a car that is two cars ahead of a particular car on the ferris wheel.

(e) At what speed, correct to the nearest 0.01 metres per second, is the trailing passenger moving upward when the other passenger is moving downward at exactly the same speed? (3 marks)

Solution
Equal speeds will occur when the 2 cars are equidistant from the y axis.
Adjacent cars are separated by $\frac{2\pi}{16} = \frac{\pi}{8}$ radians
\therefore For the trailing car $\theta = \frac{7\pi}{8}$ or $t = \frac{63}{2} = 31.5$ sec.
$\therefore Speed = y'\left(\frac{7\pi}{8}\right) = 80\cos\left(\frac{3\pi}{8}\right) \times \frac{\pi}{36}$
= 2.6716 m/sec
Hence the equal speeds is 2.67 m/sec (nearest 0.01)
Specific behaviours
\checkmark states the position for each car when equal speeds are achieved
\checkmark determines the correct value for θ or t for equal speeds
✓ calculates the speed (no penalty for incorrect rounding)

(4 marks)

Question 19

Two parallel planes Π_1 and Π_2 have their equations given by:

$$\Pi_{1} \qquad \underline{r} \cdot \underline{n} = 11$$

$$\Pi_{2} \qquad \underline{r} \cdot \underline{n} = -4 \quad \text{where } \underline{n} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

It is known that the point (2,3,–7) is a point on plane \prod_1 . Prove the distance *d* between the point (2,3,–7) and plane \prod_2 is given by

$$d = \frac{15}{\sqrt{a^2 + b^2 + c^2}} \; .$$



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